

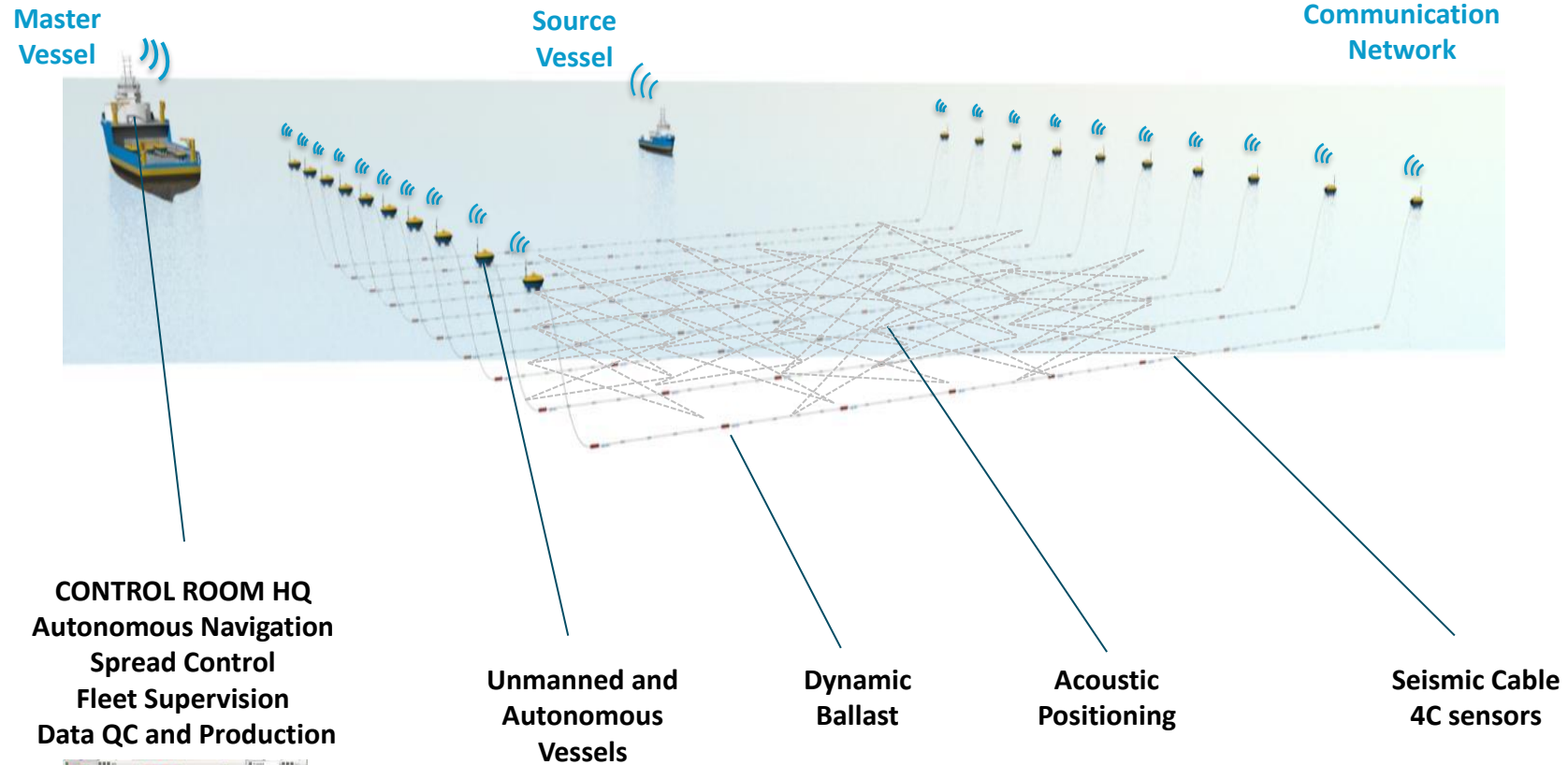


# Unmanned and Autonomous Offshore Exploration Technology

Jan 25<sup>th</sup> 2021

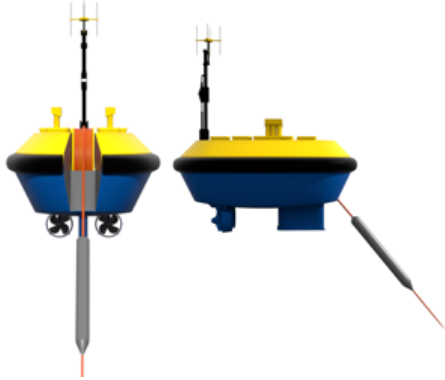
Meeting Kietta - Orsted

# Autonomous Marine Seismic Acquisition using a Fleet of Unmanned Vessels





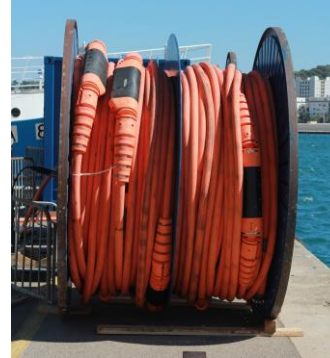
# Technology Bricks specifically designed



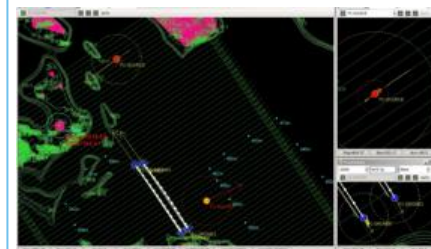
Recording Autonomous Vehicle (RAV)



Ballast unit



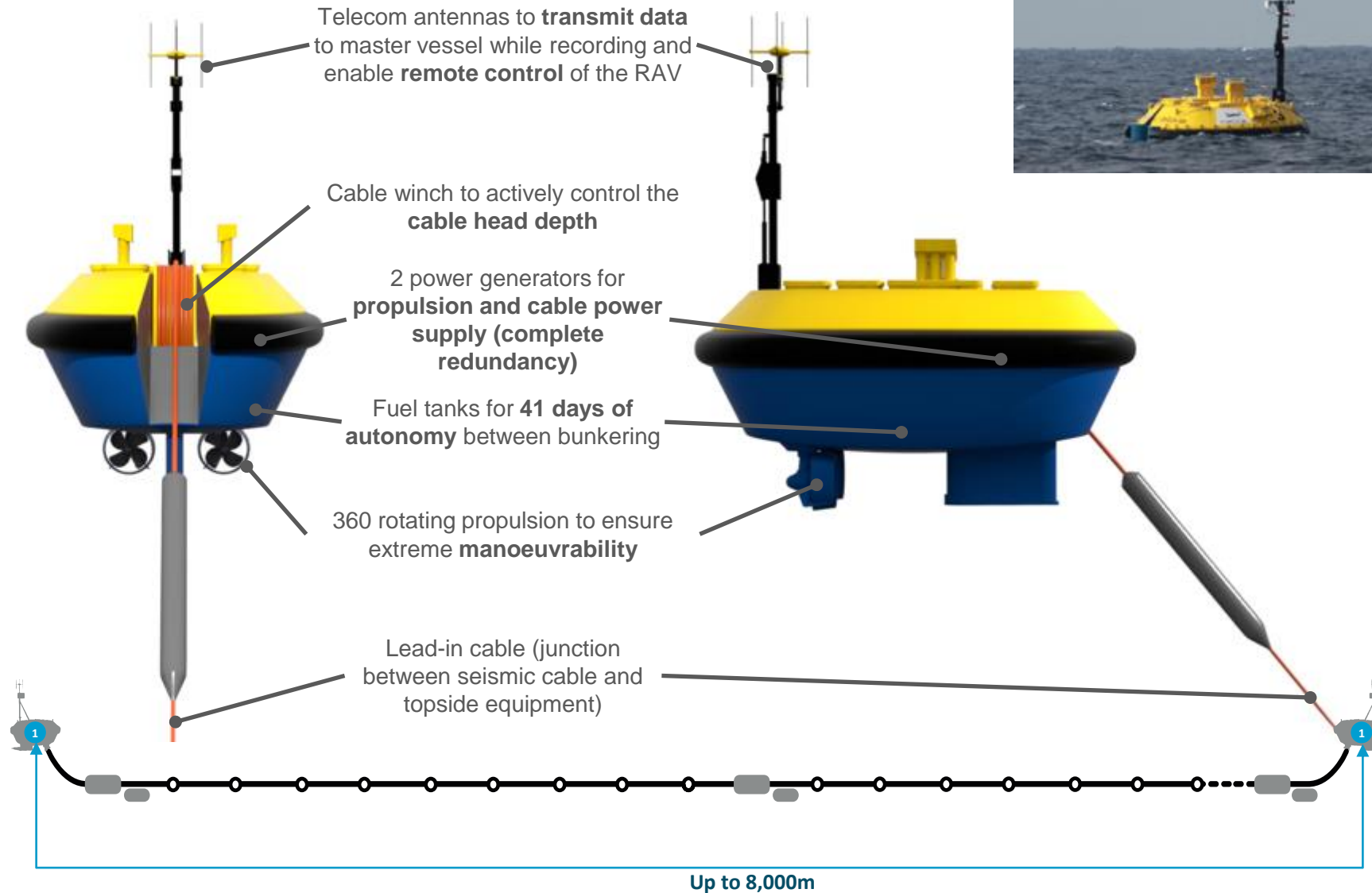
Seismic Cable



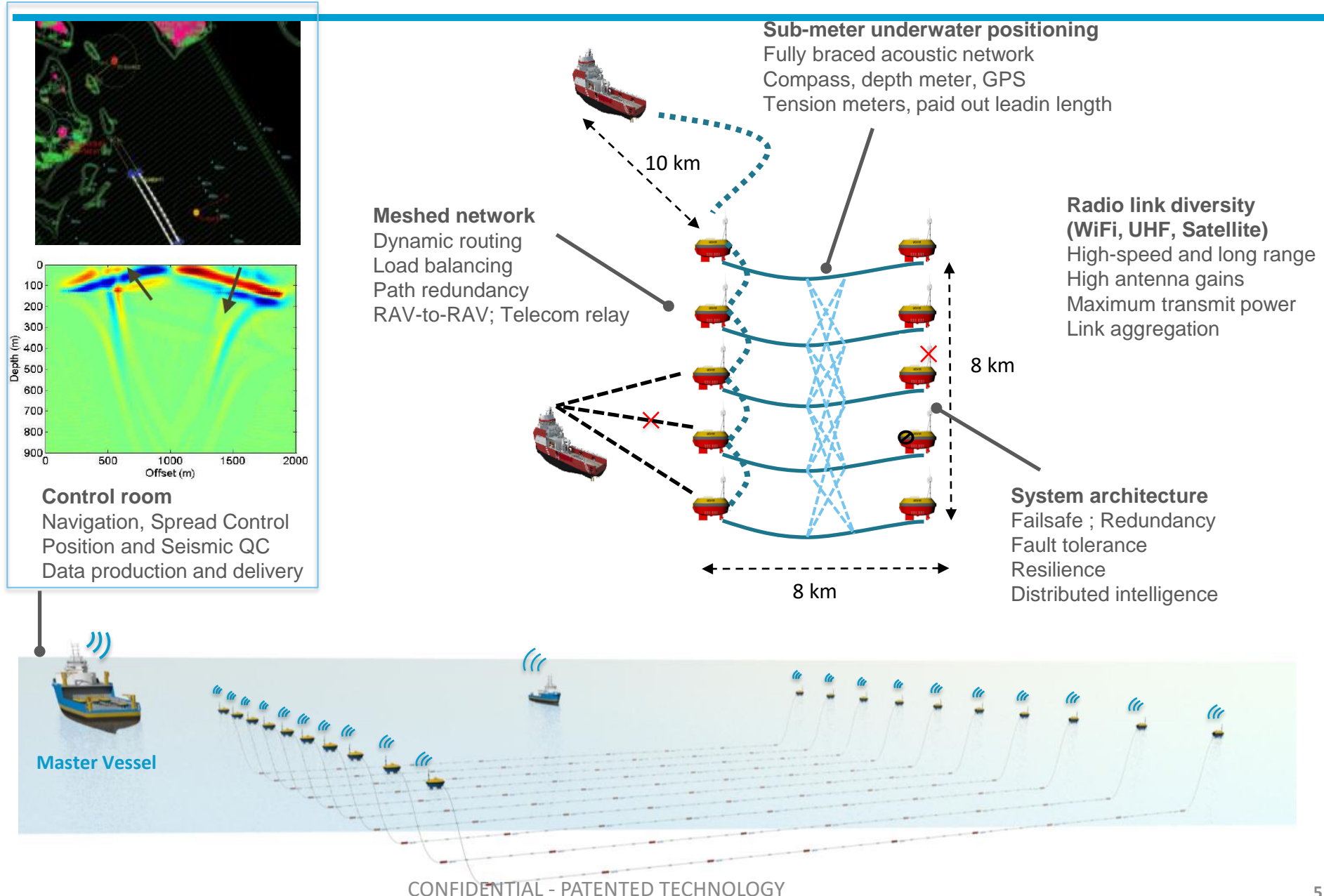
Real-time control and QC system

Patent families: FR2945356, FR2961317, FR2990028, FR3043791, FR3046129, FR3054890

# Recording Autonomous Vessel (RAV)

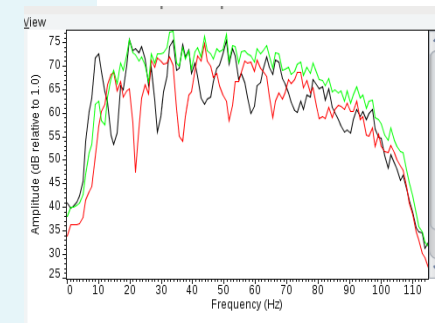
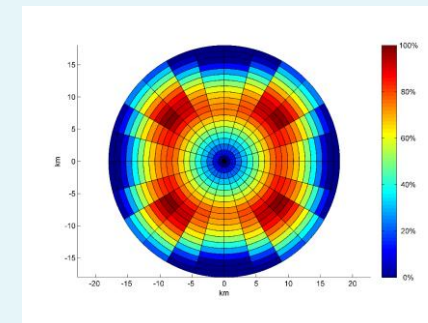


# Real-time Spread and Quality Control



# What we bring to the seismic market

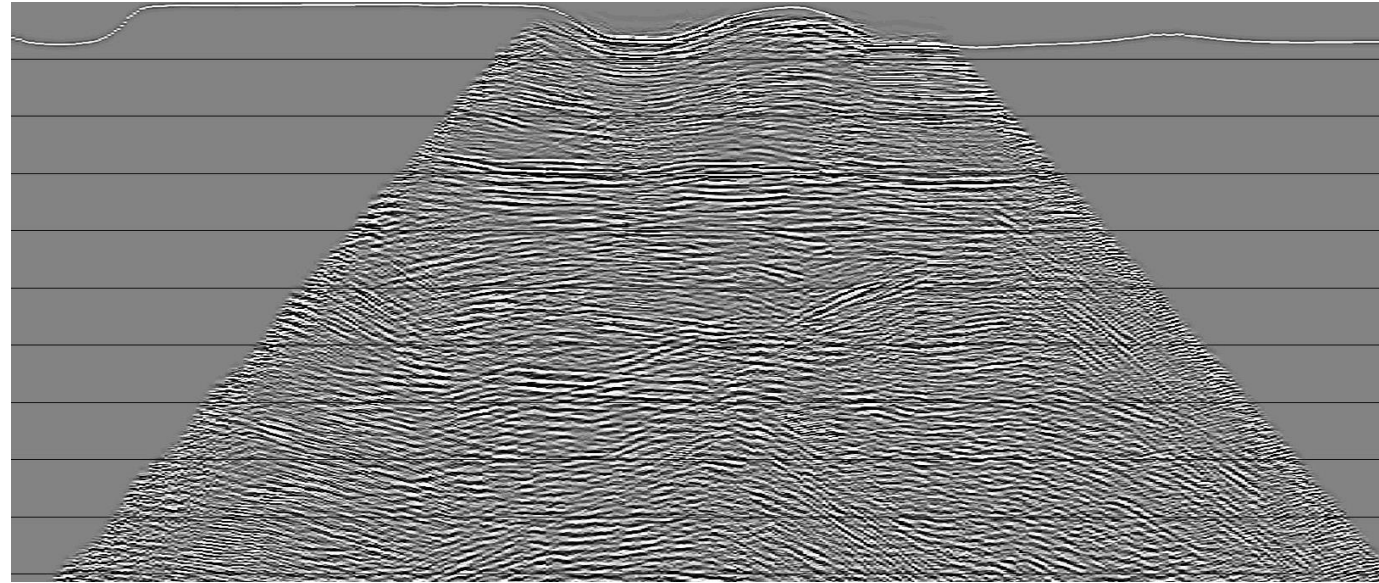
- **High productivity**
  - **Reduced acquisition time** compared to existing technologies for a given data quality
  - **Potential for improvement:** ready for simultaneous operations
- **HSE higher standards and environmentally friendly**
  - Autonomous vessels leading to less people on-site
  - Less fuel consumption / Less pollution
  - No impact on sea bottoms, no damage on sea flora, no risk with sea bottom installations
- **Streamlined operational expenses**
  - Only vessels of opportunities required for operations
  - Optimized set up of operations thanks to system flexibility
- **Superior Data Quality**
  - Full azimuth illumination, full band
  - Low Acquisition Noise
  - Real Time Data Access (Superior Data Quality Control)
  - ⇒ Resulting in more precise subsurface imaging





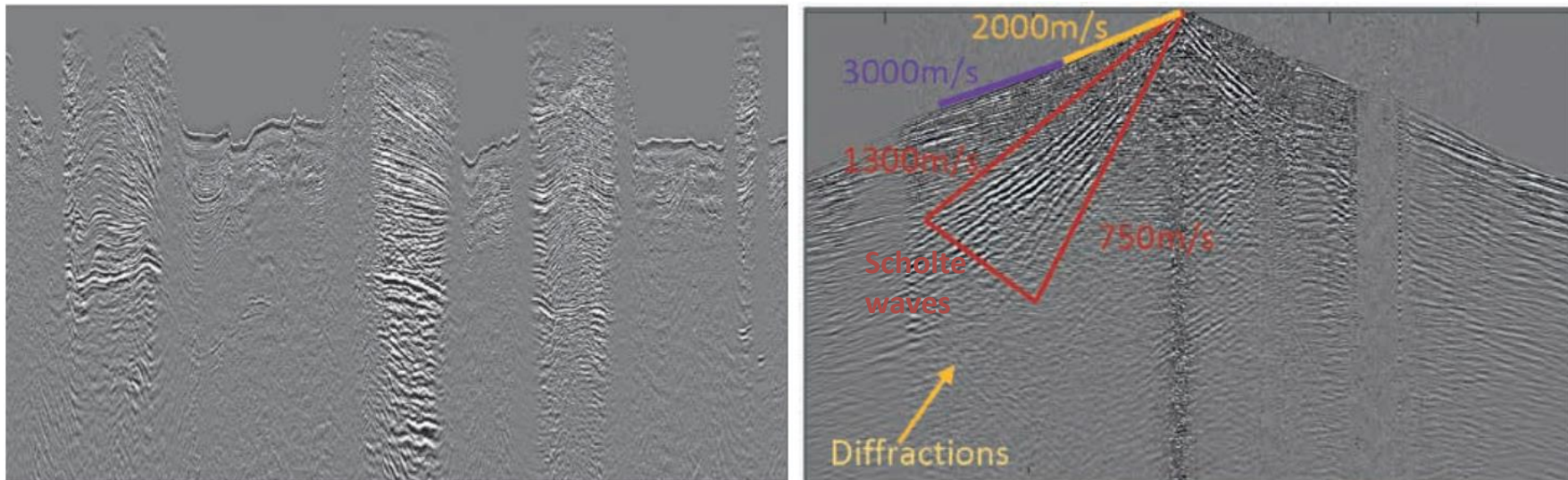
# Superior Subsurface Image from Seabed Downwards

Homogeneous image with high quality



FreeCable  
acquisition

Heterogeneous quality with noise degradations



OBN  
acquisition in  
the same area

Source: First Break,  
volume 35, Nov. 2017

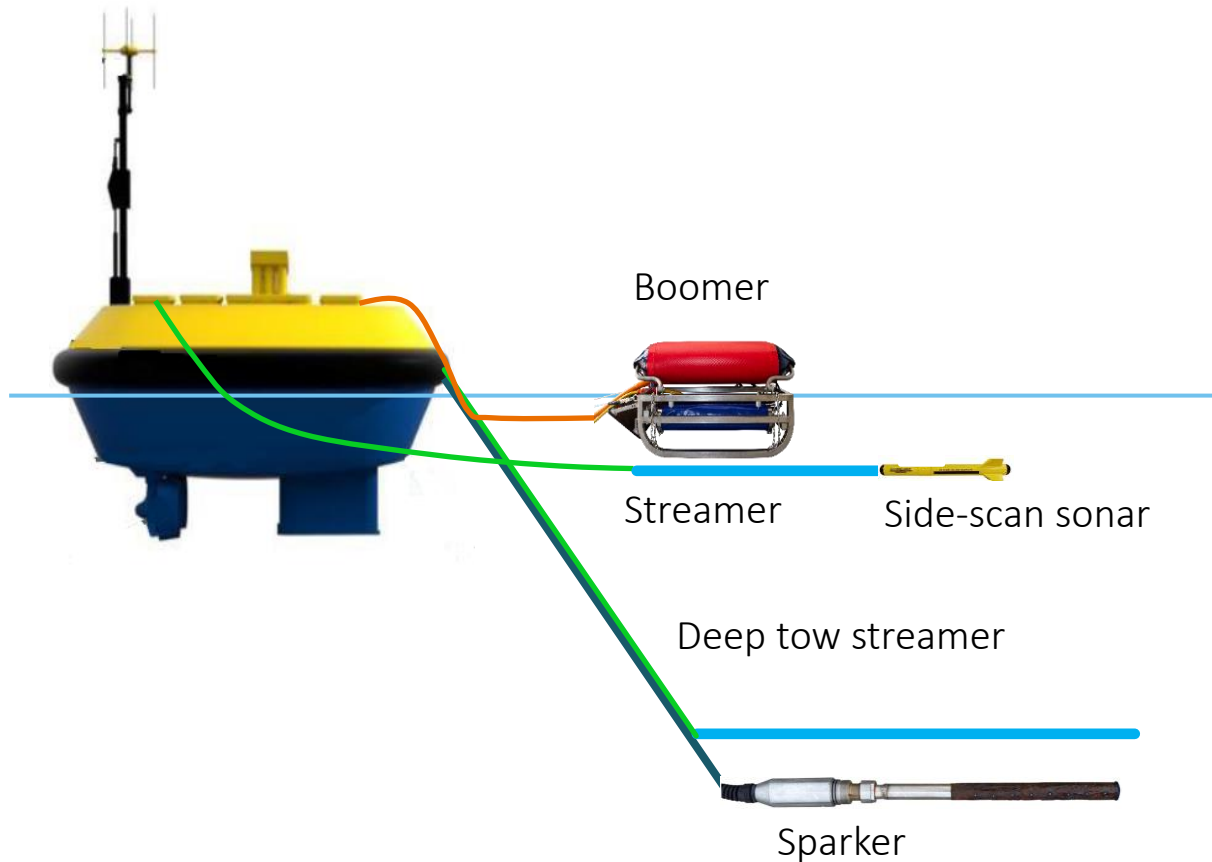
## We can bring similar benefits to offshore windfarm markets

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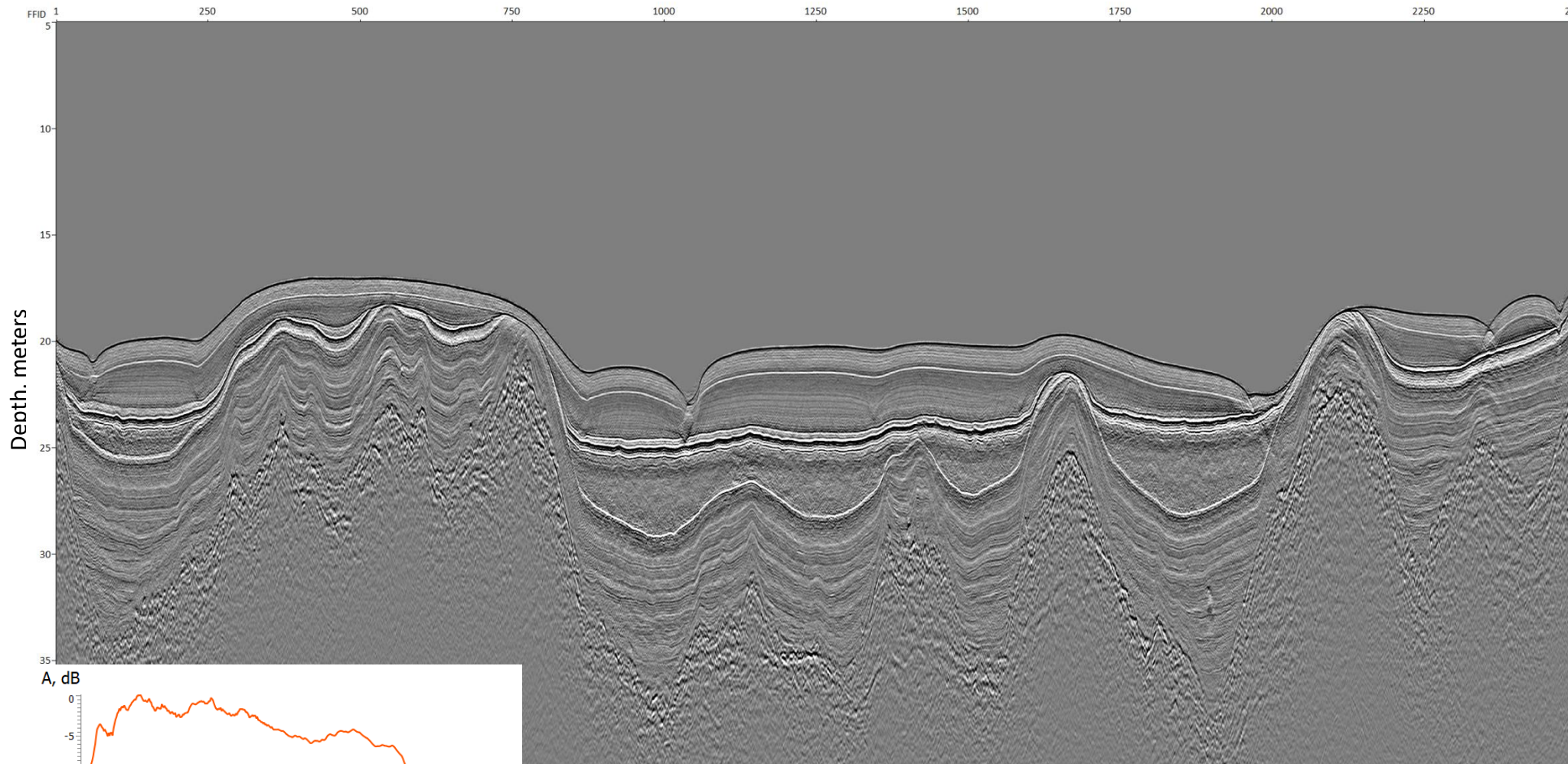
## Configuration to image 0-100m area









Example of configuration with:

- Very high-resolution seismic equipment
- Seabed mapping (SSS)

Other configurations are possible depending on customer requirements

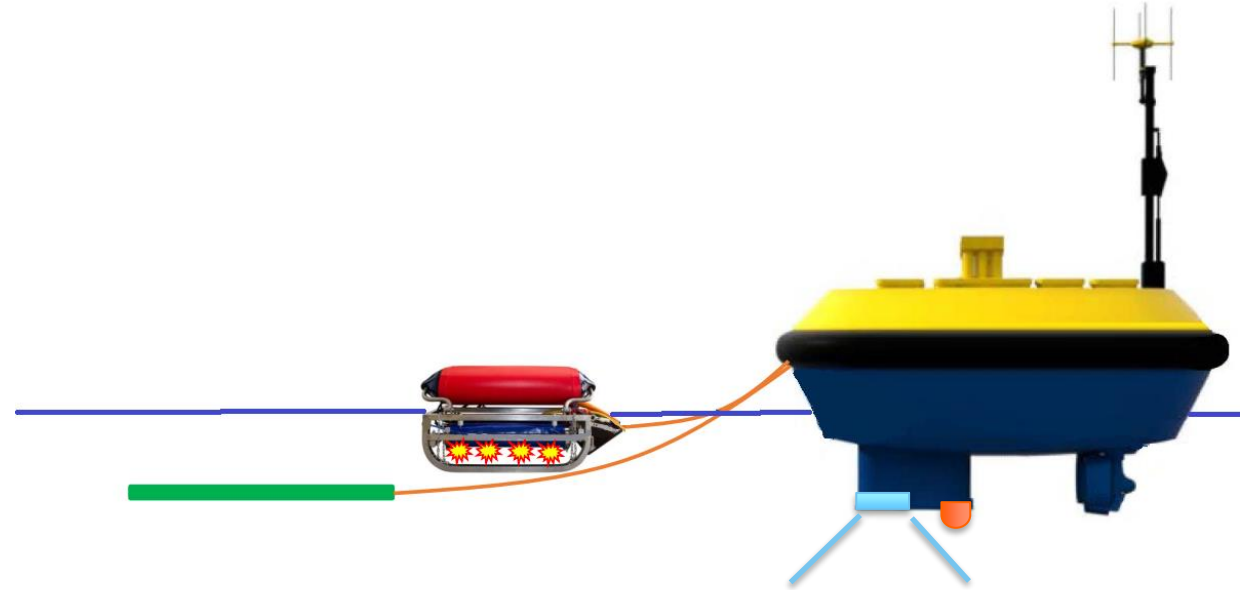


	MultiJack 2500HP3.0
	FWS-250
	HRStreamer 1-ch data
	Geodevice
	17-23 m
	Lake Ladoga

# Integration of multi-physics measurements

Multiple equipment can be mounted or towed:

- High resolution seismic (source and streamer)
- Electromagnetic
- Magnetometer
- Sonar (SSS, multi-beam)
- Echosounder
- Bathymetry
- Current profiler



UHRs streamer



Electrodynamic boomer



Sparker



## A unique Unmanned Vessel: endurance, robust, high sea state, powerful

Overall size: L x l x H	8.20 x 5.5 x 4 m (bottom keel to deck)
Mast height	5.8 m
Draft	2.4 m
Weight	21 tons
Autonomy	41 days (subject to use and sea conditions)
Power	2 x 100 kW diesel electric generators
Propulsion	2 x azimuthal thrusters
Bollard pull	3 tons
Winch (pulling capacity)	Up to 4.5 tons
Sailing speed	Up to 5 knots
Compartment	3 (electronic room, engine room and thruster room)
Current profiler	300 kHz Workhorse Sentinel ADCP
Positioning	GNSS (PPP) with INS
Radio links	Iridium, UHF, 2.4 and 5 GHz
Others	Anemometer, NTP server, deck camera



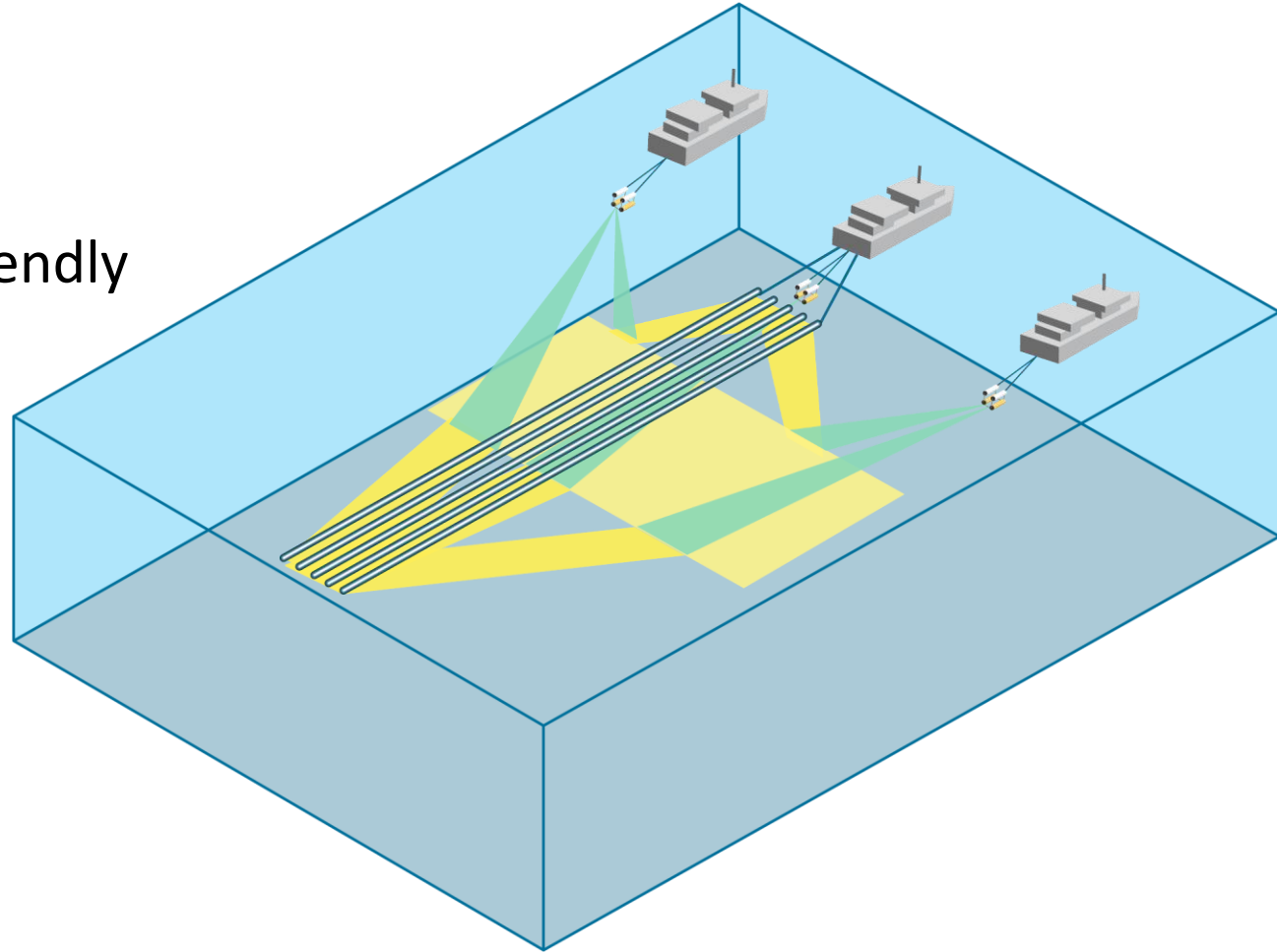
### Client's payload options

Umbilical	400 m armored cable with data fiber optic and power wire
Keel	Integrated compartment inside the keel.

Optimize cost vs. performance trade-off

- Higher quality
- Higher productivity

Safer, faster, and environment friendly





# Kietta

**Thank you for your attention**  
**Any question?**